

DISPERSION COMPENSATOR AND METHOD
OF COMPENSATING FOR DISPERSION

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Background of the Invention:

Field of the Invention:

The invention lies in the field of optics technology. More specifically, the invention relates to an optical dispersion compensator, preferably for use preceding an optical transmission link or following an optical transmission link, comprising at least one optical input, at least one frequency demultiplexer (FDM) which splits incoming signals with an input spectrum into two frequency bands f_L and f_H and two transmission links (Mach-Zehnder-Arms) of different optical lengths each of which is supplied with a frequency band (f_L , f_H), the optically longer Mach-Zehnder arm being used as delay line, and then at least one frequency recombination unit in which the two spectrally divided signals are recombined and conducted to at least one optical output.

The invention also relates to a method of compensating for the dispersion of an optical signal, transmitted via an optical fiber, having a frequency spectrum composed of two frequency bands f_H and f_L . The frequency bands are split to one Mach-

Zehnder arm each, subjected to different propagation delays,
and then combined again.

During the transmission of optical signals of a particular
5 frequency spectrum (a particular band width) via an optical
conductor of great length, for example an optical fiber,
dispersion phenomena occur due to the frequency-dependent
velocity of propagation of the light in the optical fibers,
that is to say a distortion of the input light pulse/input bit
10 sequence in dependence on the path length. This chromatic
dispersion of the optical fibers limits the maximum distance
which can be spanned with the high-bit-rate transmission
systems. Thus, for example, the usual single-mode optical
fibers with a dispersion of 17 ps/nm*km at a wavelength of
15 1550 nm allow a distance of only 80-100 km (50-65 miles) in
10 Gbit/s systems which can be spanned without dispersion
compensation. Any further doubling of the transmission band
width reduces the maximum distance which can be spanned
roughly by a factor of 4. The dispersion of the optical fiber
20 must then be correspondingly compensated for in the case of
longer transmission links.

Due to their significance for the high-bit-rate transmission
systems, there are a very large number of previously known
25 methods for dispersion compensation. They can be roughly

divided into electronic compensation techniques and optical compensation techniques.

Among the electronic compensation methods, there are firstly
5 the pre-chirp techniques. They are based on generating a
negative frequency chirp of the laser diode, thus providing
for appropriate precompensation. Furthermore, a reduction of
the input band width can be achieved by suitable modulation
methods such as single-sideband modulation, duo-binary
10 modulation etc. and thus the maximum distance which can be
spanned can be increased, the bit rate remaining the same.

The electronic compensation techniques are generally quite
cumbersome and their implementation depends on the bit rate to
15 be transmitted. A further problem consists in that electronic
compensation techniques are not optically transparent.

In the optical compensation methods, attempts are made to
simulate the dispersion of the transmission link by a
20 corresponding opposite dispersion of the optical compensation
element as completely as possible. With an optimum simulation
of the dispersion including the higher-order dispersion terms
and disregarding the non-linear effects, a complete
compensation can be potentially achieved.

For the optical dispersion compensation, special dispersion compensating fibers (DCFs) were developed which are now widely used in optical transmission systems. In this case, a bit sequence passes through the appropriately dimensioned DCF either before or after the actual dispersive transmission link section. Given the dispersion values of the DCFs which are currently achieved, a DCF length of approximately 15 km is needed for compensating for a 100 km transmission link via standard single-mode fibers.

Although these DCFs are optically transparent and allow for multi-channel compensation, they suffer from not being very compact, have an attenuation which is not negligible, and have no adjustable dispersion. The length of the DCF must be appropriately readjusted for each transmission link which entails additional logistical problems.

Another optical compensation technique is based on the "chirped" Bragg gratings (implemented fiber-optically or integrated optically). Although the "chirped" Bragg gratings are somewhat more compact than the DCFs, they operate in reflection mode and must thus be combined with a circulator. Moreover, the dispersion band width of a grating is limited and each individual wavelength channel must be separately compensated for. Furthermore, Bragg gratings which can be adjusted over a wide range of dispersion cannot be easily

achieved because, in addition, the compensation band width and the reflection coefficient are dependent on the adjusted dispersion.

5 Another possibility consists in implementing dispersion compensation circuits by integrated optical means in planar technology, fiber-optically or volume-optically with the aid of interferometric configurations. The interferometric configurations are based on the use of asymmetric Mach-Zehnder
10 interferometers, ring resonators or the Fabry-Perot resonators.

Regarding the compensation techniques described above, relating to Mach-Zehnder, reference is had to the following
15 documents:

- K. Takiguchi, K. Okamoto and K. Moriwaki, "Planar Lightwave Circuit Dispersion Equalizer", J. Lightwave Technol., vol. 14, pp. 2003-11, 1996;
- K. Takiguchi, S. Kawanishi, H. Takara, A. Himeno. K.
20 Hattori, "Dispersion Slope Equalizer for Dispersion Shifted Fiber Using a Lattice-Form Programmable Optical Filter on a Planar Lightwave Circuit", J. Lightwave Technol., vol. 16, pp. 1647-56, 1998; and

- K. Jinguji, M. Kawachi, "Synthesis of Coherent Two-Port Lattice-Form Optical Delay-Line Circuit", J. Lightwave Technol., vol. 13, pp. 73-82, 1995;

5 Relating to ring resonators and Fabry-Perot, reference is had to the following reference:

- C.K. Madsen, G. Lenz, 'Optical All-Pass Filters for Phase Response Design with Applications for Dispersion Compensation", IEEE Photon. Technol. Lett., vol. 10, pp. 994-96, 1998.

The contents of the foregoing references are herewith incorporated by reference.

15 A technical problem of the above-mentioned interferometric structures consists in that, without cascading, they only provide for very limited dispersion compensation while simultaneously requiring a wide dispersion band width. The cascading necessary for this, in turn, unavoidably leads to a
20 structure which is increasingly more difficult to implement and is more complex.

Summary of the Invention:

The object of the present invention is to provide a dispersion
25 compensator and a method for compensating for dispersion which

overcome the above-noted deficiencies and disadvantages of the prior art devices and methods of this general kind, and wherein the system is capable of compensating for high dispersion values without cascading a number of filter stages and which, at the same time, has a wide band width.

Furthermore, the invention is intended to make it possible to generate adjustable dispersion values.

With the above and other objects in view there is provided, in accordance with the invention, an optical dispersion compensator, comprising:

an optical input receiving an incoming signal having an input spectrum;

a frequency demultiplexer connected to the input and configured to split the incoming signal into two frequency bands;

two transmission links formed as Mach-Zehnder arms connected to the frequency demultiplexer and each receiving a respective one of the two frequency bands, the transmission links including an optically shorter transmission link and an optically longer transmission link acting as a delay line;

a polarization converter connected in at least one of the two transmission links; and

at least one frequency recombination unit connected to the two transmission links for recombining the signals received from the first and second transmission links, and an optical output for outputting the combined signal.

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The dispersion compensator is preferably connected to receive the incoming signal from an optical transmission link and/or to output an optical signal recombined from the spectrally divided signals to an optical transmission link.

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In further summary, the inventor proposes here a structure which provides for high dispersion compensation at any dispersion band width without cascading a number of filter stages. It is based on combining the two part-signals of an asymmetric Mach-Zehnder without forming interference in spite of an existing coherence. This is possible when the two signals are mutually orthogonally polarized when the signal is being recombined.

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20 According to this concept of the invention, the optical dispersion compensator is improved - and specifically suitable for use preceding an optical transmission link or following an optical transmission link - in that there are provided at least one optical input, at least one frequency demultiplexer
25 (FDM) which splits incoming signals having an input spectrum into two frequency bands f_L and f_H and two transmission links

(Mach-Zehnder arms) of different optical lengths, each of which is supplied with a frequency band (f_L , f_H), the optically longer Mach-Zehnder arm being used as delay line, and then at least one frequency recombination unit in which the two

5 spectrally divided signals are recombined and conducted to at least one optical output, to such an extent that a polarization converter is provided in at least one Mach-Zehnder arm. This is preferably the Mach-Zehnder arm having the shorter optical length for constructional considerations.

10 According to the invention, this dispersion compensator can be mounted either preceding or following an optical data transmission link.

15 In accordance with an added feature of the invention, the frequency recombination unit is a TE/TM polarization combiner or a 3-dB coupler.

In accordance with an additional feature of the invention, at

20 least one of the transmission links is split into two or more partial links. A driven $1 \times N$ switch and a driven $N \times 1$ switch are provided (N is an integer > 1) and N partial links are connected between the switches. Preferably, the $1 \times N$ switch and the $N \times 1$ switch are thermo- or electro-optically driven.

In accordance with another feature of the invention, a TE/TM phase shifter is connected in at least one of the transmission links. The TE/TM phase shifter may be connected behind, i.e., downstream of, the polarization converter.

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With the above and other objects in view there is also provided, in accordance with the invention, an optical signal link which comprises a dispersion compensator as outlined above and a polarization controller connected upstream of the optical input of the dispersion compensator.

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In accordance with a further preferred embodiment, the polarization controller is formed with two Mach-Zehnder arms and a phase shifter in at least one of the Mach-Zehnder arms.

Furthermore, the polarization controller further comprises a TE/TM divider at an input and a frequency recombination unit at an output thereof, and the two Mach-Zehnder arms of the polarization controller are connected between the TE/TM

20 divider and the frequency recombination unit.

In accordance with again another feature of the invention, a polarization converter is connected in at least one of the Mach-Zehnder arms of the polarization controller.

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The optical signal link is further characterized in that the polarization controller further comprises a bipolar polarization converter and mode sorter at an input thereof and a frequency recombination unit at an output thereof, and
5 wherein the at least two Mach-Zehnder arms of the polarization controller are connected between the bipolar polarization converter and mode sorter and the frequency recombination unit.

10 With the above and other objects in view there is also provided, in accordance with the invention, an optical signal link formed with the dispersion compensator outlined above and a polarization scrambler and a polarizer (TE mode or TM mode) connected to the optical input of the dispersion compensator.

15 As noted above, an advantageous refinement of the dispersion compensator provides for the multiplexer to be implemented in the form of a TE/TM polarization combiner. This is possible if the two recombination signals supplied orthogonally are
20 polarized in accordance with the respective principal axes (TE and TM). In this case, the two signals are theoretically combined without 3dB power loss. As an alternative, a 3dB coupler can also be used which then, however, causes the power loss.

In addition, the dispersion compensator can be designed in such a manner that at least one Mach-Zehnder arm, preferably the arm having the longer optical length and/or without polarization converter, is split into at least two part-links
5 (into N part-links in general), in which case a drivable $1 \times N$ switch, a drivable $N \times 1$ switch and N part-links between the switches are provided. The result is that the delay time of the part-frequency band, and thus the achievable dispersion, becomes adjustable.

In this refinement of the dispersion compensator according to the invention, the $1 \times N$ switch and $N \times 1$ switch can be operated, for example, thermo-optically or electro-optically, without excluding other variants.

If there is no linearly polarized polarization state at the input of the compensator or there is a linearly polarized input state which does not correspond to the directions of the principal axis of the wave guides of the compensator and, at
15 the same time, the wave guides of the compensator are anisotropically constructed, the two signals with the different frequency bands are no longer orthogonally polarized when they are being combined.

25 To recover the orthogonality in this case, it is also proposed in a special refinement of the invention that a fast

controllable TE/TM phase shifter is arranged in at least one transmission link of the Mach-Zehnder, preferably behind the polarization converter. This makes it possible to ensure the orthogonality of the recombination signals when they are being
5 combined by suitably driving the TE/TM phase shifter in the case of anisotropic wave guides.

If the dispersion compensator is to be used following an optical signal link, it may be appropriate or even necessary
10 to linearize the polarization state coming into the dispersion compensator. This can be done by using a polarization controller in front of the dispersion compensator. This polarization controller can be implemented by a TE/TM divider at the input and a frequency recombination unit (multiplexer)
15 at the output, one of the two Mach-Zehnder arms being equipped with a polarization converter and one of the two Mach-Zehnders being equipped with a fast controllable phase shifter.

In another embodiment of the signal link, the polarization
20 controller is implemented by means of a bipolar polarization converter and mode sorter at the input and a frequency recombination unit (multiplexer) at the output where here, too, one of the two Mach-Zehnder arms needs a fast controllable phase shifter.

When the dispersion compensation element is mounted after the transmission link, there is also the possibility of mounting a fast polarization scrambler in front of the compensator and then a TE mode or TM mode polarizer. This also provides for a homogenous linear input polarization state in the compensator, an additional 3dB power loss having to be accepted in this configuration.

With the above objects in view there is also provided, in accordance with the invention, a method of compensating for a dispersion of an optical signal. The method comprises the following method steps:

transmitting an optical signal via an optical fiber, the optical signal having a frequency spectrum composed of two frequency bands f_H and f_L , splitting the frequency bands into one Mach-Zehnder arm each, and subjecting the frequency bands to different propagation delays; and

recombining the two frequency bands transmitted in the two Mach-Zehnder arms and polarized orthogonally with respect to one another when they are combined.

In other words, in the method for compensating for dispersion of an optical signal transmitted via an optical fiber, having a frequency spectrum composed of two frequency bands f_H , f_L ,

the frequency bands being split to one Mach-Zehnder arm each, being subjected to different propagation delays and then being combined again, which is characterized in that the two frequency bands are polarized orthogonally with respect to one
5 another when they are combined.

It must also be pointed out that the compensator can be implemented fiber-optically, volume-optically and/or integrated optically. Naturally, care must be taken to see
10 that the components used do not generate any additional rotations in the polarization states.

Other features which are considered as characteristic for the invention are set forth in the appended claims.
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Although the invention is illustrated and described herein as embodied in a dispersion compensator and method for compensating for dispersion, it is nevertheless not intended to be limited to the details shown, since various
20 modifications and structural changes may be made therein without departing from the spirit of the invention and within the scope and range of equivalents of the claims.

The construction and method of operation of the invention,
25 however, together with additional objects and advantages thereof will be best understood from the following description

of specific embodiments when read in connection with the accompanying drawings.

Brief Description of the Drawings:

5 Fig. 1 is a diagrammatic view illustrating the elementary functions of an (integrated-optical, fiber-optical or volume-optical) dispersion compensator based on a frequency demultiplexer, an asymmetric Mach-Zehnder and a frequency recombination unit, according to the prior art;

10 Fig. 2 is a diagrammatic view illustrating the principle of dispersion compensation by cascading an asymmetric Mach-Zehnder interferometer;

15 Fig. 3 is a diagram illustrating dispersion compensation analogously to Fig. 1 but additionally with the installation of a polarization converter in one of the two interferometer arms;

20 Fig. 4 is a diagram showing dispersion compensation as in Fig. 3 but with adjustable delay line for the f_H band of the spectrum;

Fig. 5 is a diagram showing dispersion compensation as in

25 Fig. 4 but expanded by a TE/TM phase shifter for compensating

for birefringent wave guides at any homogenous elliptical
input polarization state;

Fig. 6a illustrates dispersion compensation as in Fig. 4 but
5 with a preceding polarization controller;

Fig. 6b illustrates another version of the dispersion
compensation as in Fig. 4 with a preceding polarization
controller; and

Fig. 7 illustrates dispersion compensation as in Fig. 4 but
expanded by a preceding polarization scrambler followed by a
TE polarizer.

15 Description of the Preferred Embodiments:

Referring now to the figures of the drawing in detail and
first, particularly, to Fig. 1 thereof, there is seen a
diagrammatic illustration of a prior art assembly for
compensating for dispersion with the aid of an asymmetric

20 Mach-Zehnder interferometer having an input 15 and two outputs
(output 1 and output 2) at 16. The elementary functions
necessary for compensating for dispersion such as the spectral
division of the signal with the aid of a frequency division
multiplexer (FDM) 1, the spectrum-dependent time delay ΔL ($\Delta \tau$)
25 and the signal recombination in a multiplexer 3 are

implemented on a common starting substrate in the case of an integrated implementation.

In the example according to Fig. 1, the input frequency

5 spectrum f_L , f_H of the signal is divided by the FDM 1 into two frequency bands f_H (high frequencies) and f_L (low frequencies) to the two Mach-Zehnder arms 4.1 and 4.2. As is also shown in Fig. 1, an adjustable phase shifter 2 for adjusting the phase difference $\Delta\phi$, which may be based on the thermo-optical or
10 electro-optical effect, is additionally necessary for precise phase calibration in one of the interferometer arms. Following this, the separated signals are recombined via the multiplexer 3.

15 This configuration represents a filter stage. The phase relationship of the waves interfering in the multiplexer 3 must not change too much as a function of the frequency in order to be able to achieve the desired compensation band widths without much intensity and time delay ripple. However,
20 this requirement limits the maximum achievable delay time $\Delta\tau$, and thus the dispersion per filter stage.

As a consequence, it is only possible to achieve large dispersion compensation over a great band width by cascading a
25 number of asymmetric Mach-Zehnders (filter stages). Such an

implementation, normally used in the prior art, is shown in Fig. 2. The individual asymmetric Mach-Zehnder interferometers are here connected to one another by directional couplers 5 and, at the same time, fulfill the functions of frequency division multiplex, frequency-dependent delay, and frequency division demultiplex.

Due to the cascading, a progressive coherent overloading of the wave components of the two interferometer arms is generated. The greater the desired dispersion compensation with simultaneous large band width, the more cascading stages are required. Thus, the implementation becomes increasingly more difficult, especially since the optical path length or, respectively, the phase of each interferometer or, respectively, of each filter stage, must be precisely monitored. This may be done by a thermo-optical phase shifter. Configurations with virtually arbitrarily adjustable compensation values, possibly by means of adjustable couplers, are conceivable but again increase the complexity.

Fig. 3 shows a structure according to the invention of an optical dispersion compensator analogously to Fig. 1. Here, however, a polarization converter 6 is additionally inserted in the Mach-Zehnder arm 4.1 (interferometer arms). The aim is to achieve a signal recombination of two frequency bands without interference being formed due to their orthogonal

polarization states. By appropriately dimensioning ΔL
(difference in length of the Mach-Zehnder arms), time delays
 Δt of the frequency band f_H can be achieved which have any
magnitude, and this with a total band width of the signal $f_L +$
5 f_H which, at the same time, is of any magnitude.

The assembly firstly consists of the frequency demultiplexer
(FDM) 1 which divides the input spectrum into two frequency
bands f_L and f_H . The FDM 1 ideally has a rectangular frequency
10 response, i.e. having edges which drop off as steeply as
possible. In the asymmetric Mach-Zehnder interferometer
following, the two frequency bands f_L and f_H are subjected to a
different propagation delay. In the case of isotropic and, at
the same time, polarization-maintaining wave guides as is
15 basically possible, for example, with an integrated optical
form of implementation, the polarization input state as drawn
in Fig. 3 can have any elliptical shape. The polarization
states are specified by the configuration of the ellipses
shown. The polarization converter then converts the signal of
20 the Mach-Zehnder arm 4.1 from an arbitrarily elliptically
polarized state into an elliptically polarized signal which is
orthogonal thereto. This signal is then combined with the
time-delayed signal from the Mach-Zehnder arm 4.2 in the
multiplexer 3.

The multiplexer 3 in which the two frequency bands are combined and superimposed again may consist, in a simple implementation, of a broad band 3dB coupler which entails an additional power loss of about 3dB. In that case, an output of
5 the multiplexer 3 can be used as monitor output. This can be used for monitoring the output power.

If, as shown in Fig. 3, the configuration consists of isotropic wave guides, an arbitrary elliptical polarization state of the input signal is permissible for its correct operation and the ellipse should be as identical as possible over the entire channel band width. In the case of a linear input polarization state with identical axes, the multiplexer can be implemented by a TE/TM polarization combiner which
10 makes it possible to combine the signals without 3dB power loss.

In the case of weakly or non-dispersive wave guides, the dispersion of the transmission link is only roughly
20 approximated by the two-stage time delay which, however, can lead to a considerable improvement in the signal. Suitable dimensioning of the delay line ΔL can result in a two-stage time delay $\Delta \tau$ of any magnitude without cascading which means considerable simplification, especially in the case of large
25 compensation values. Furthermore, the configuration manages

without an adjustable phase shifter. The configuration thus needs no further corrective control with permanently set FDM, polarization converter and multiplexer.

- 5 If the dispersion of the transmission link is to be simulated ideally, it can be attempted to use in the Mach-Zehnder arms dispersive wave guides which have to be especially developed for the purpose.

10 Fig. 4 shows a variant of the structure shown in Fig. 3 with adjustable time delay. For this purpose, two adjustable switches 7 and 8 which, depending on how they are driven, apply the f_H band of the spectrum to a corresponding delay line of different length 4.2.1 ... 4.2.N, are inserted in the Mach-
15 Zehnder arm 4.2. The switches can be driven, for example, thermo-optically or electro-optically. This configuration, too, does not need any phase shifter for precise phase calibration.

- 20 The configuration shown in Fig. 4 requires, analogously to Fig. 3, ideally either an identical homogenous input polarization state over the entire channel frequency band width and, at the same time, isotropic wave guides, or a linear TE or TM input polarization state with arbitrarily
25 anisotropic wave guides to function correctly. The configurations according to Figs. 3 and 4 are, therefore,

particularly suitable for dispersion compensation preceding the transmission link, for instance directly following the transmit laser with its defined linear polarization state.

5 If the configuration according to Fig. 4 can only be implemented by means of anisotropic wave guides, it is necessary to use an adjustable TE/TM phase shifter 9 in one of the two Mach-Zehnder arms to obtain correct operation of the dispersion compensator with an arbitrary homogenous elliptical
10 input polarization state. As shown in Fig. 5, this phase shifter can be arranged, for example, following the polarization converter 6. The phase shifter 9 ensures that the two interferometer signals in the Mach-Zehnder arms 4.1 and 4.2 are orthogonal when they are combined. In this
15 configuration, the TE/TEM phase shifter 9 must compensate for the accumulated difference in anisotropy of the two Mach-Zehnder arms.

For the general case of anisotropic wave guides of the
20 dispersion compensator, the input polarization state can also be rotated by an additional preceding polarization controller in such a manner that it is linearly polarized and, at the same time, corresponds to one of the wave guide axes of the dispersion compensator.

Such an embodiment can be indicated especially if the dispersion compensator according to the invention is used following a transmission link. As a supplement to the embodiments known in the literature, Figs. 6a and 6b show two configurations which are possible for this purpose.

The polarization controller 17 of the configurations according to Figs. 6a, 6b controls the polarization state in such a manner that it corresponds to the principal axes of the wave guides of the subsequent dispersion compensator 18 (TE or TM polarization). The principal axes of the wave guides of the subsequent dispersion compensator 18 are thus allowed to have any anisotropy. At the same time, the polarization controllers 17 of Figs. 6a, 6b can be used for compensating for the polarization mode dispersion to a limited extent.

As a further variant for an application of the configurations following the transmission link as shown in Figs. 3 and 4, it would be conceivable to use a preceding fast polarization scrambler 13 followed by a TE or TM polarizer 14. In this case, the wave guides 4.1, 4.2 of the dispersion compensator 18 are allowed to have any anisotropy since the input polarization state of the light wave is oriented in the direction of one of the principal axes (TE or TM polarization) by the preceding polarizer 14. The polarization scrambler 13 is used either at the link input or directly before the

compensation element with the preceding polarizer. In any case, the polarizer should be used immediately preceding the actual compensator element.

5 As an example, Fig. 7 shows a configuration with a polarization scrambler 13 and TE polarizer 14 directly preceding the dispersion compensator 18.

In this configuration with polarization scrambler and downstream polarizer, an additional power loss of 3dB must be accepted.

All configurations described can be used for single-channel or multi-channel compensation in dependence on the nature of the transmission link. The configurations can be implemented either integrated-optically (on a common substrate in integrated or hybrid form), fiber-optically or with the aid of micro-optical (volume-optical) components.

20 Thus, the invention describes a method for compensating for dispersion and a dispersion compensator for carrying out the method, an optical signal being split into two frequency bands f_H and f_L and to two Mach-Zehnder arms, there being subjected to different propagation delays and the frequency bands subsequently being recombined and polarized orthogonally with respect to one another.

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